

# Diagnosis (03)

## Incremental Diagnosis and De Kleer Theory

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Incremental Diagnosis

De Kleer Theory

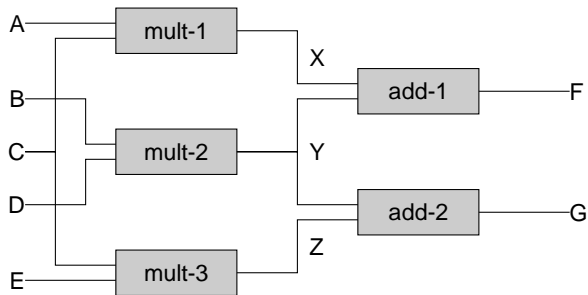
Other problems

## Incremental Diagnosis

De Kleer Theory

Other problems

# Davis Circuit



# Why an incremental computation?

- ▶ Some observations are not known at first. Solutions:
  1. Wait until all the observations are present
  2. Compute a diagnosis, and re-compute it when new observations are given
  3. Compute a diagnosis, and incrementally refine it
- ▶ A cost is associated with some observations, we prefer not to use it if we do not need
  1. First perform a diagnosis with some observations, and incrementally add new observations if we need

► Definition

A Reiter Diagnosis  $\Delta$  predicts  $O$  iff

$$SD \cup OBS \cup \{\neg Ab(c) \mid c \in COMP \setminus \Delta\} \cup \{Ab(c) \mid c \in \Delta\} \models O$$

► Example: Davis Circuit

- $\Delta_1 = \{m_1\}$  predicts  $Out(m_2) = 6$
- $\Delta_2 = \{m_2, m_3\}$  predicts  $Out(m_2) = 4$  and  $Out(m_3) = 6$

# Confirmation and invalidation

- ▶ Confirmation
  - ▶ A Reiter Diagnosis  $\Delta$  for  $(SD, COMP, OBS)$  that predicts  $O$  is a Reiter Diagnosis for  $(SD, COMP, OBS \cup \{O\})$
- ▶ Invalidation
  - ▶ A Reiter Diagnosis  $\Delta$  for  $(SD, COMP, OBS)$  that predicts  $\neg O$  is not a Reiter Diagnosis for  $(SD, COMP, OBS \cup \{O\})$

Let  $\Delta$  be a Reiter Diagnosis for  $(SD, COMP, OBS)$ , let  $O$  be a new observation

- ▶ If  $\Delta$  predicts  $O$ , then  $\Delta$  is confirmed
- ▶ If  $\Delta$  predicts  $\neg O$ , then look at supersets of  $\Delta$
  
- ▶ Let  $O$  be an observation that confirms the Reiter Diagnosis  $\Delta_1$  and invalidates  $\Delta_2$  for  $(SD, COMP, OBS)$ . We say that  $O$  **discriminates**  $\Delta_1$  and  $\Delta_2$

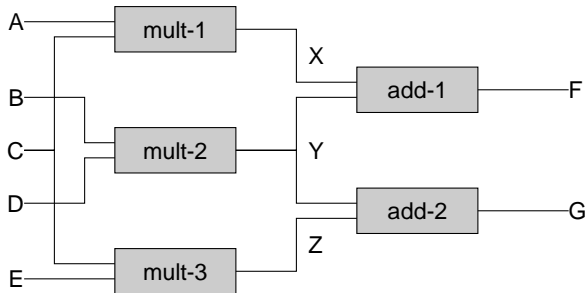
- ▶ A system ( $SD, COMP$ ) is **diagnosable** if for any set of possible measurements (any complete set of observations) we have a unique diagnosis
- ▶ Example (Davis Circuit):
  - ▶ If we can observe  $A, B, C, D, E, F, G$ , then the system is not diagnosable
  - ▶ If we can observe  $A, B, C, D, E, F, G, X, Y, Z$  then the system is diagnosable

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# Problem of Reiter Theory



New piece of information on the system (failure knowledge):

$$Ab(m_1) \Rightarrow Out(a_1, 0)$$

A super set of a Reiter Diagnosis is not always a diagnosis

► Definition

Let  $C$  and  $D$  be a conjunction of literals

- $C$  covers  $D$  iff any literal of  $C$  is a literal of  $D$

► Example

- $C = Ab(c_1) \wedge \neg Ab(c_2)$  covers  
 $D = Ab(c_1) \wedge \neg Ab(c_2) \wedge Ab(c_3)$
- $C = Ab(c_1) \wedge \neg Ab(c_2)$  does not cover  
 $D = Ab(c_1) \wedge Ab(c_2) \wedge Ab(c_3)$

# How to represent the diagnoses?

- ▶ Problem

$n$  components  $\Rightarrow 2^n$  states

- ▶ Intuition

$Ab(c_1) \wedge \neg Ab(c_2) \wedge Ab(c_3)$

$Ab(c_1) \wedge \neg Ab(c_2) \wedge \neg Ab(c_3)$

Partial diagnosis =  $Ab(c_1) \wedge \neg Ab(c_2)$

- ▶ Definition

A partial diagnosis is an Ab-clause  $\Phi$  such that any state  $e$  covered by  $\Phi$  is a diagnosis

# Kernel diagnosis

- ▶ Definition
  - ▶ A kernel diagnosis is a partial diagnosis that is not covered by any partial diagnosis
- ▶ Example
  - ▶ State Diagnoses
    - ▶  $Ab(c_1) \wedge Ab(c_2) \wedge Ab(c_3)$
    - ▶  $Ab(c_1) \wedge Ab(c_2) \wedge \neg Ab(c_3)$
    - ▶  $Ab(c_1) \wedge \neg Ab(c_2) \wedge Ab(c_3)$
    - ▶  $Ab(c_1) \wedge \neg Ab(c_2) \wedge \neg Ab(c_3)$
    - ▶  $\neg Ab(c_1) \wedge Ab(c_2) \wedge Ab(c_3)$
  - ▶ Partial diagnoses that are not states
    - ▶  $Ab(c_1) \wedge Ab(c_2)$
    - ▶  $Ab(c_1) \wedge Ab(c_3)$
    - ▶  $Ab(c_1) \wedge \neg Ab(c_2)$
    - ▶  $Ab(c_1) \wedge \neg Ab(c_3)$
    - ▶  $Ab(c_1)$

- ▶ A conflict is an Ab-clause that is a deduction of  $SD \cup OBS$
- ▶ A conflict is minimal if no sub clause is a conflict
- ▶ A positiv conflict is such that all the literals are positiv

# Link between minimal diagnoses and kernel diagnoses

► Theorem

all the minimal conflicts are positiv



any kernel diagnosis (De Kleer) is a minimal diagnosis  
(Reiter)

# Which diagnosis to choose?

- ▶ The kernel diagnosis that contains the fewest faulty components
- ▶ Explanatory diagnoses

# Explanatory diagnosis

- ▶ A diagnosis  $\Delta$  for  $(SD, COMP, OBS)$  **explains** an observation  $o$  iff  $SD \cup OBS \models o$
  
- ▶ Example (Davis Circuit)
  - ▶  $Ab(a_1) \wedge \neg Ab(a_2) \wedge \neg Ab(m_1) \wedge \neg Ab(m_2) \wedge \neg Ab(m_3) \models Out(a_2, 12)$
  - ▶  $\neg Ab(a_1) \wedge Ab(a_2) \wedge \neg Ab(m_1) \wedge Ab(m_2) \wedge \neg Ab(m_3) \not\models Out(a_2, 12)$
  
- ▶ Which observations to explain?
  - ▶ All the observations?
  - ▶ The biggest number of observations of  $OBS$ ?
  - ▶ The normal observations?

Incremental Diagnosis

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Other problems

- ▶ Non monotonicity
  - ▶ Monotonicity: if  $KB \models \alpha$ , then  $KB \wedge \beta \models \alpha$
  - ▶ Problem: exceptions (example, all the bird flies, so the emu does!)
  - ▶ Non monotonic logics
- ▶ Uncertainty
  - ▶ We considered the knowledge is complete
  - ▶ How to express and make reasoning about ignorance, uncertainty, incompleteness?
  - ▶ Probability theory: Bayesian Networks, Markov Decision Process, Fuzzy logic